

Span: Does $\{v_1, v_2, \dots, v_t\}$ span V ? \Rightarrow $\text{Span}\{v_1, v_2, \dots, v_t\} = V$

#elements = t

Can we generate all vectors in V as a linear comb. of these vectors?

$$r_1 v_1 + r_2 v_2 + \dots + r_t v_t = \text{a typical vector in } V$$

system of linear equations

if this system has a solution for r_1, r_2, \dots, r_t (without any restrictions) $\Rightarrow \checkmark$

\rightarrow if the system may not have a solution $\Rightarrow \times$

$t < \dim(V) \Rightarrow$ The set can not span V .

$t = \dim(V) \Rightarrow$ a square system $\det \neq 0 \Rightarrow \checkmark$ $\det = 0 \Rightarrow \times$

$t > \dim(V) \Rightarrow$ may or may not span $V \rightarrow$ solve the system.

Linear Independence: Is $\{v_1, v_2, \dots, v_t\}$ linearly independent?

#elements = t

$$c_1 v_1 + c_2 v_2 + \dots + c_t v_t = \vec{0}_V$$

a system of linear equations

$\vec{0}_V$ in the set $\Rightarrow \times$
if the vectors can be written as a linear comb. $\Rightarrow \times$

$c_1 = c_2 = \dots = c_t = 0 \rightarrow$ trivial soln. is the only soln. $\Rightarrow \checkmark$

inf. many soln. case $\Rightarrow \times$

$t < \dim(V) \Rightarrow$ may or may not be lin. indep. \rightarrow solve the system.

$t = \dim(V) \Rightarrow$ square system $\det \neq 0 \Rightarrow \checkmark$ $\det = 0 \Rightarrow \times$

$t > \dim(V) \Rightarrow$ the set can not be lin. independent \times

BASIS: $\{v_1, v_2, \dots, v_t\}$ span + lin. indep.

$t = \dim(V)$, $\det \neq 0$
 \Downarrow
Dimension

$2v_1 + 3v_2 + \dots + 5v_t = \text{Hakil}$
 $-1v_1 + 4v_2 + \dots + 0v_t = \text{Cihan F.}$

standard bases

$$\begin{bmatrix} a \\ b \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \end{bmatrix} = c \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

standard bases

$$\dim(\mathbb{R}^3) = 3 \quad \mathbb{R}^3 \quad \left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}_{e_2}, \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{e_3} \right\} = E \quad \begin{bmatrix} a \\ b \\ c \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\dim(\mathbb{R}^2) = 2 \quad \mathbb{R}^2 \quad \left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 \\ 1 \end{bmatrix}}_{e_2} \right\} = E$$

$$\dim(\mathbb{R}^{2 \times 2}) = 4 \quad \mathbb{R}^{2 \times 2} \quad \left\{ \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_{e_2}, \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}_{e_3}, \underbrace{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}}_{e_4} \right\} = E$$

$$\dim(\mathbb{P}_3) = 3 \quad \mathbb{P}_3 \quad \{1, x, x^2\} \quad ax^2 + bx + c$$

Finding a Basis for Subspaces

any subspace dimension \leq dimension of the superspace

Ex

Problem 2. ANSWERS ONLY CHECKED - ANSWERS NOT RECORDED

(4 points) Let V be the vector space of symmetric 2×2 matrices and W be the subspace

$\dim(\mathbb{R}^{2 \times 2}) = 4$

Find a nonzero element X in W .

$X = \begin{bmatrix} 1 & 2 \\ 2 & 0 \end{bmatrix}$

(Gives credit only if all entries of the matrix are true)

Entered	Answer Preview	Correct	Result
$\begin{bmatrix} 1 & 2 \\ 2 & 0 \end{bmatrix}$	$\begin{bmatrix} 1 & 2 \\ 2 & 0 \end{bmatrix}$	incorrect	incorrect

This answer is NOT correct.

$\rightarrow W = \text{span} \left\{ \underbrace{\begin{bmatrix} -1 & -2 \\ -2 & -2 \end{bmatrix}}_{v_1}, \underbrace{\begin{bmatrix} 2 & 4 \\ 4 & 2 \end{bmatrix}}_{v_2} \right\} \subseteq \mathbb{R}^{2 \times 2}$

$\rightarrow W = \{ r v_1 + s v_2 : r, s \in \mathbb{R} \}$

$v_1 + 0 v_2$ $\{v_1, v_2\}$ spans W

$\{v_1, v_2\}$ is also lin. indep. \rightarrow is this a basis W ?

! if you're given 2 vector (whatever vector space you're in), the only possible linear combination \rightarrow scalar multiple.

Ex

$$S = \left\{ r \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + s \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix} : r, s, t \in \mathbb{R} \right\} \quad \text{Find a basis for } S. \quad \dim(S) = ?$$

(S is a subspace of \mathbb{R}^3)

$$= \text{span} \left\{ \underbrace{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}}_{v_1}, \underbrace{\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}}_{v_2}, \cancel{\underbrace{\begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix}}_{v_3}} \right\}$$

$\{v_1, v_2, v_3\}$ already spans S .

$v_3 = v_1 + v_2 \rightarrow$ we don't need v_3 . $\{v_1, v_2, v_3\}$ is not linearly indep.

$\{v_1, v_2\}$ is a linearly independent. still spans S .

A basis for $S = \{v_1, v_2\}$

A basis for $S = \{v_1, v_2\}$

$\dim(S) = 2$

$\mathbb{R}^2 \not\subseteq \mathbb{R}^3$

Ex

In $v_1 = 1+x$ $v_2 = x^2$ $v_3 = 2x^2-3$

$\in \mathbb{P}_4$

$\mathbb{P}_2 \subseteq \mathbb{P}_3 \subseteq \mathbb{P}_4$

$S = \text{Span}\{v_1, v_2, v_3\}$ Find a basis for S . $\dim(S) = ?$

$\{v_1, v_2, v_3\}$ spans S . Is $\{v_1, v_2, v_3\}$ lin. independent?

$c_1 v_1 + c_2 v_2 + c_3 v_3 = 0 + 0x + 0x^2 + 0x^3 \rightarrow 0_{\mathbb{P}_4}$

$c_1(1+x) + c_2(x^2) + c_3(2x^2-3) = 0 + 0x + 0x^2 + 0x^3 \rightarrow 0_{\mathbb{P}_4}$

$\rightarrow c_1 - 3c_3 = 0 \Rightarrow c_3 = 0$

$c_1 = 0$

$c_2 + 2c_3 = 0 \Rightarrow c_2 = 0$

$0 = 0$

$c_1 = c_2 = c_3 = 0$ is the only solution of the system.

$\Rightarrow \{v_1, v_2, v_3\}$ is a linearly independent set.

(*)

(*) + (**) $\Rightarrow \{v_1, v_2, v_3\}$ is a basis for S .

$\dim(S) = 3$

Change of Bases

\mathbb{R}^3

any vector in this space

$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} = E$

e_1

e_2

e_3

we fix the order

$F = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix} \right\}$ is a basis for \mathbb{R}^3

$\begin{vmatrix} 1 & -1 & 0 \\ 2 & 0 & 0 \\ 3 & 1 & 4 \end{vmatrix} = -2 \begin{vmatrix} -1 & 0 \\ 1 & 4 \end{vmatrix} + 0 + 0 = 8 \neq 0$

Ex

$A_{y \text{ seg}^{-1}} = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix} \in \mathbb{R}^3 \rightarrow v$

$v = \begin{bmatrix} [v] \\ 1 \end{bmatrix}_E$

$A_{y \text{ seg}^{-1}} = 5e_1 + 8e_2 + 3e_3$

$A_{y \text{ seg}^{-1}} = r_1 v_1 + r_2 v_2 + r_3 v_3$

$[v]_F$ coordinates of $A_{y \text{ seg}^{-1}}$ with respect to the basis $F = \{v_1, v_2, v_3\}$

$F = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix} \right\}$

Assume that you want to find r_1, r_2, r_3

$$F = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix} \right\}$$

Assume that you want to find r_1, r_2, r_3

$$1 = (v_1, v_2, v_3)$$

$$r_1 v_1 + r_2 v_2 + r_3 v_3 = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix} \Rightarrow r_1 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + r_2 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} + r_3 \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix}$$

$$Ax=b$$

$$\begin{cases} r_1 - r_2 + 0r_3 = 5 \\ 2r_1 + 0r_2 + 0r_3 = 8 \\ 3r_1 + r_2 + 4r_3 = 3 \end{cases}$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & -1 & 0 & 5 \\ 2 & 0 & 0 & 8 \\ 3 & 1 & 4 & 3 \end{array} \right]$$

$$\Rightarrow \begin{bmatrix} 1 & -1 & 0 \\ 2 & 0 & 0 \\ 3 & 1 & 4 \end{bmatrix} \begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix}$$

$$B = \{w_1, w_2, w_3\}$$

$$F \begin{bmatrix} v \\ \vdots \end{bmatrix}_F = v$$

$$F^{-1} F \begin{bmatrix} v \\ \vdots \end{bmatrix}_F = \begin{bmatrix} v \\ \vdots \end{bmatrix}$$

det $\neq 0$
 F^{-1} exists \checkmark

B, C two ordered basis for V

(we don't know $v \in V$)

Knowing B, C , and $[v]_B \Rightarrow$ how can we find $[v]_C = ?$

$$\cancel{v} = B [v]_B = C [v]_C$$

$$\Rightarrow C^{-1} B [v]_B = C^{-1} C [v]_C = [v]_C$$

This matrix is called as the transition matrix from B to C .

Ex We're in \mathbb{R}^2
 Halil $= v = \begin{bmatrix} 4 \\ 6 \end{bmatrix}$

$$B = \left\{ \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 4 \end{bmatrix} \right\}$$

$$C = \left\{ \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \end{bmatrix} \right\}$$

$$\det = 12 - 10 = 2 \neq 0 \checkmark$$

$$\det C = -2 - 0 = -2 \neq 0 \checkmark$$

B and C are two ordered basis in \mathbb{R}^2 .

$$v = B [v]_B = C [v]_C = \dots$$

$$[v]_B = B^{-1} v = \begin{bmatrix} 2 & -5/2 \\ -1 & 3/2 \end{bmatrix} \begin{bmatrix} 4 \\ 6 \end{bmatrix} = \begin{bmatrix} -7 \\ 5 \end{bmatrix}$$

\Rightarrow coordinates of Halil wrt the basis B .

Short way to find A^{-1}

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$B = \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$$

$$B^{-1} = \begin{bmatrix} 4/2 & -5/2 \\ -2/2 & 3/2 \end{bmatrix} = \begin{bmatrix} 2 & -5/2 \\ -1 & 3/2 \end{bmatrix}$$

Short way to find 2x2 inverses

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\begin{bmatrix} 2 \\ 2 \end{bmatrix} \quad \det B = 2$$

$$\begin{bmatrix} -2 & 3 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 3/2 \end{bmatrix}$$

$$-7 \begin{bmatrix} 3 \\ 2 \end{bmatrix} + 5 \begin{bmatrix} 5 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix} \rightarrow \text{Halil} \checkmark$$

-21 + 15
-14 + 20

Ex

$$B = \left\{ \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 4 \end{bmatrix} \right\}$$

$$\det = 12 - 10 = 2 \neq 0 \checkmark$$

$$C = \left\{ \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \end{bmatrix} \right\}$$

$$\det C = -2 - 0 = -2 \neq 0 \checkmark$$

$$[v]_B = \begin{bmatrix} -7 \\ 5 \end{bmatrix}$$

a) Find the transition matrix from B to C.

$$B [v]_B = C [v]_C$$

$$[v]_C = C^{-1} B [v]_B$$

b) $[v]_C = ?$

$$C = \begin{bmatrix} -1 & 5 \\ 0 & 2 \end{bmatrix} \quad \det C = -2$$

$$C^{-1} = \begin{bmatrix} 2/2 & -5/2 \\ 0 & 1/2 \end{bmatrix} = \begin{bmatrix} 1 & -5/2 \\ 0 & 1/2 \end{bmatrix}$$

$$C^{-1} B = \begin{bmatrix} -1 & 5/2 \\ 0 & 1/2 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 1 & 2 \end{bmatrix}$$

0+1 0+2

the transition matrix from B to C.

$$b) [v]_C = C^{-1} B [v]_B = \begin{bmatrix} 2 & 5 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} -7 \\ 5 \end{bmatrix} = \begin{bmatrix} 11 \\ 3 \end{bmatrix} = [v]_C$$

to check:

$$11 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 5 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix} \rightarrow \text{Halil} \checkmark$$

-11 + 15
0 + 6

7. Given

$$v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \quad S = \begin{bmatrix} 3 & 5 \\ 1 & -2 \end{bmatrix} \rightarrow \text{from } B \text{ to } C = C^{-1} B \checkmark$$

find vectors w_1 and w_2 so that S will be the transition matrix from $\{w_1, w_2\}$ to $\{v_1, v_2\}$.

$$B = \{w_1, w_2\} \quad C = \{v_1, v_2\}$$

$$C = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix} \right\}$$

$$C = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$$

$$C (C^{-1} B) = B$$

I S

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 1 & -2 \end{bmatrix} = \begin{bmatrix} 5 & 1 \\ 5 & 1 \end{bmatrix} \rightarrow R = \left\{ \begin{bmatrix} 5 \\ 5 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

$$\begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 3 \\ 5 \\ 1 \\ -2 \end{pmatrix} = \begin{bmatrix} 5 & 1 \\ 9 & 4 \end{bmatrix} \xrightarrow{I} B = \left\{ \begin{bmatrix} 5 \\ 9 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \end{bmatrix} \right\}$$

\downarrow w_1 \downarrow w_2

8. Given

$$v_1 = \begin{pmatrix} 2 \\ 6 \end{pmatrix}, \quad v_2 = \begin{pmatrix} 1 \\ 4 \end{pmatrix},$$

$$B = \begin{bmatrix} 2 & 1 \\ 6 & 4 \end{bmatrix}$$

$\det = 8 - 6 = 2$

$$B^{-1} = \begin{bmatrix} 4/2 & -1/2 \\ -6/2 & 2/2 \end{bmatrix}$$

$$B^{-1} = \begin{bmatrix} 2 & -1/2 \\ -3 & 1 \end{bmatrix}$$

$$S = \begin{bmatrix} 4 & 1 \\ 2 & 1 \end{bmatrix}$$

$C^{-1}B$ ✓

find vectors u_1 and u_2 so that S will be the transition matrix from $\{v_1, v_2\}$ to $\{u_1, u_2\}$.

$$\begin{matrix} \textcircled{B} & \textcircled{C} \\ \checkmark & ? \end{matrix}$$

$$C^{-1}B$$

✓

$$B$$

✓

$$C = ?$$

Find B^{-1} .

$$\underbrace{C^{-1}B}_{I} B^{-1} = C^{-1} \Rightarrow (C^{-1})^{-1} = C$$

$$C^{-1} = \frac{C^{-1}B B^{-1}}{5} = \begin{bmatrix} 4 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1/2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} 5 & -1 \\ 1 & 0 \end{bmatrix}$$

$\begin{matrix} 8-1 & -2+1 \\ -1+1 \end{matrix}$

$$\det C^{-1} = 0 - (-1) = 1$$

$$C = \begin{bmatrix} 0 & 1 \\ -1 & 5 \end{bmatrix}$$

$$\Rightarrow C = \left\{ \underbrace{\begin{bmatrix} 0 \\ -1 \end{bmatrix}}_{u_1}, \underbrace{\begin{bmatrix} 1 \\ 5 \end{bmatrix}}_{u_2} \right\}$$